

3.46 Determine the expression for the frequency response of each of the LTI discrete-time systems of Figure 2.35 in terms of the frequency responses $H_i(e^{j\omega})$, $1 \leq i \leq 4$, of the individual blocks.

3.65 An FIR filter of length 3 is defined by a symmetric impulse response; that is, $h[0] = h[2]$. Let the input to this filter be a sum of two cosine sequences of angular frequencies 0.3 rad/samples and 0.6 rad/samples, respectively. Determine the impulse response coefficients so that the filter passes only the low-frequency component of the input.

3.79 Determine the expressions for the group delay of each of the LTI systems whose frequency responses are given below.

$$(a) H_a(e^{j\omega}) = a + be^{-j\omega}, \quad (b) H_b(e^{j\omega}) = \frac{1}{1+ce^{-j\omega}}, \quad (c) H_c(e^{j\omega}) = \frac{a+be^{-j\omega}}{1+ce^{-j\omega}}, \quad |c| < 1,$$

$$(d) H_b(e^{j\omega}) = \frac{1}{(1+ce^{-j\omega})(1+de^{-j\omega})}, \quad |c| < 1, \quad |d| < 1.$$

M 3.8 Write a MATLAB program to simulate the filter designed in Problem 3.65, and verify its filtering operation.

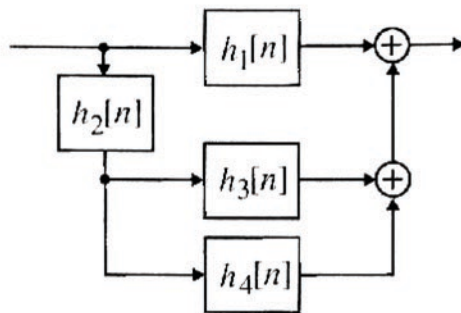


Figure 2.35: The discrete-time system of Example 2.35.

$$h_1[n] = \delta[n] + \frac{1}{2}\delta[n-1], \quad h_2[n] = \frac{1}{2}\delta[n] - \frac{1}{4}\delta[n-1],$$

$$h_3[n] = 2\delta[n], \quad h_4[n] = -2\left(\frac{1}{2}\right)^n \mu[n].$$